18 - 21 NOVEMBER, 2018, BENGALURU, INDIA

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## 18 - 21 NOVEMBER, 2018, BENGALURU, INDIA

Session	IC-IEEE Symposium on Immune Computation
Date/Time	November 19, 2018 (Monday) 03:20 - 05:20 hrs
Venue	Jupiter 1
Chair	Soumya Banerjee
SS-1201	Robotic Immune Systems: An Architecture Yamin Hu and Wenjian Luo
SS-1206	dnyNSA: A Novel Real-Value Based Negative Selection Algorithm Zhang Fan, Yang Jin, Li Tao and Zhu Fangdong
SS-1194	A Two-Factor Authentication Scheme based on Negative Databases Ran Liu, Xiang Wang and Can Wang
SS-1254	Reconstructing Positive Surveys from Negative Surveys by Improved Artificial Immune Network Ran Liu, Mengxi Xie and Siqi Sun
SS-1479	For a Refoundation of Artificial Immune System Research: AIS is a Design Pattern Pierre Parrend, Fabio Guigou, Julio Navarro, Aline Deruyver and Pierre Collet
SS-1381	An Immune based Dynamic Risk Control System Ping Lin, Jin Yang, Tao Li and Lei Ai
Session	ADPRL-1-IEEE Symposium on Adaptive Dynamic Programming and Reinforcement Learning
Session  Date/Time	ADPRL-1-IEEE Symposium on Adaptive Dynamic Programming and Reinforcement Learning  November 19, 2018 (Monday) 03:20 - 05:20 hrs
Date/Time	November 19, 2018 (Monday) 03:20 - 05:20 hrs
Date/Time Venue	November 19, 2018 (Monday) 03:20 - 05:20 hrs  Ceres
Date/Time Venue Chair	November 19, 2018 (Monday) 03:20 - 05:20 hrs  Ceres  Jagannathan Sarangapani  A Game Theoretic Based Biologically-Inspired Distributed Intelligent Flocking Control for Multi-UAV Systems with Network Imperfections
Date/Time Venue Chair SS-1337	November 19, 2018 (Monday) 03:20 - 05:20 hrs  Ceres  Jagannathan Sarangapani  A Game Theoretic Based Biologically-Inspired Distributed Intelligent Flocking Control for Multi-UAV Systems with Network Imperfections  Mohammad Jafari and Hao Xu  Multi-Robot Enhanced MANET Routing with Situation Aware Online Reinforcement Learning
Date/Time Venue Chair SS-1337 SS-1176	November 19, 2018 (Monday) 03:20 - 05:20 hrs  Ceres  Jagannathan Sarangapani  A Game Theoretic Based Biologically-Inspired Distributed Intelligent Flocking Control for Multi-UAV Systems with Network Imperfections  Mohammad Jafari and Hao Xu  Multi-Robot Enhanced MANET Routing with Situation Aware Online Reinforcement  Learning  Ming Feng and Hao Xu  Learning to Play Pac-Xon with Q-Learning and Two Double Q-Learning Variants

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# SS-1179 On the Use of Dropouts in Neural Networks for System Identification and Control Shrikanth M. Yadav and Koshy George

Session	DL-1-Deep Learning
Date/Time	November 20, 2018 (Tuesday) 09:00 - 11:00 hrs
Venue	Jupiter 2
Chair	Mahardhika Pratama
SS-1183	Improving Shallow Neural Network by Compressing Deep Neural Network  Marcus Carvalho and Mahardhika Pratama
SS-1232	A Robot Localization Framework Using CNNs for Object Detection and Pose Estimation Lukas Hoyer, Christoph Steup and Sanaz Mostaghim
SS-1064	A Dataset and Preliminary Results for Umpire Pose Detection using SVM Classification of Deep Features  Aravind Ravi, Harshwin Venugopal, Sruthy Paul and Hamid R. Tizhoosh
SS-1316	Extra Domain Data Generation with Generative Adversarial Nets  Luuk Boulogne, Klaas Dijkstra and Marco Wiering
SS-1373	Text Summarization as Tree Transduction by Top-Down TreeLSTM  Davide Bacciu and Antonio Bruno
SS-1440	Perception Net: A Multimodal Deep Neural Network for Machine Perception  Dhruv Bhandari and Sandeep Paul
Session	ADPRL-2-IEEE Symposium on Adaptive Dynamic Programming and Reinforcement Learning
Date/Time	November 20, 2018 (Tuesday) 09:00 - 11:00 hrs
Venue	Ceres
Chair	Jagannathan Sarangapani
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SS-1390	Visual Sparse Bayesian Reinforcement Learning: A Framework for Interpreting What an Agent Has Learned Indrajeet Mishra, Giang Dao and Minwoo Lee
SS-1390 SS-1338	Visual Sparse Bayesian Reinforcement Learning: A Framework for Interpreting What an Agent Has Learned

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Session	ADPRL-3-IEEE Symposium on Adaptive Dynamic Programming and Reinforcement Learning
Date/Time	November 20, 2018 (Tuesday) 11:20 - 01:00 hrs
Venue	Ceres
Chair	Jagannathan Sarangapani
SS-1200	Learning TWSVM using Privilege Information  Aman Pal and Reshma Rastogi
SS-1520	Reward based Single Network Adaptive Critic for Optimal Kinematic Control of a Redundant Robot Manipulator  Jenin Jose, Ravi Prakash and Laxmidhar Behera
Session	MCDM-4-IEEE Symposium on Multi-Criteria Decision Making
Date/Time	November 20, 2018 (Tuesday) 11:20 - 01:00 hrs
Venue	Neptune
Chair	Jussi Hakanen
SS-1425	Understanding Collective Decision-Making in Natural Swarms Asema Hassan and Sanaz Mostaghim
SS-1043	A Performance Indicator for Reference-Point-Based Multiobjective Evolutionary Optimization Zhanglu Hou, Shengxiang Yang, Juan Zou, Jinhua Zheng, Guo Yu and Gan Ruan
SS-1288	A Topologically Consistent Visualization of High Dimensional Pareto-front for Multi-Criteria Decision Making AKM Khaled Ahsan Talukder and Kalyanmoy Deb
SS-1358	Reference Point Based NSGA-III for Preferred Solutions Yash Vesikar, Kalyanmoy Deb and Julian Blank